civilconstruction.trimble.com

Trimble MPS566 Model 2

Modular GNSS heading receiver

Precise positioning and heading, anywhere

Advanced

- Trimble® ProPoint® GNSS
 positioning engine. Engineered for
 improved accuracy and productivity
 in challenging GNSS conditions.
- Trimble Maxwell™ 7 GNSS ASIC dual chipset tracks the latest signals from all GNSS constellations with improved Trimble EVEREST™ Plus multipath mitigation, interference detection and protection against GNSS spoofing.
- Trimble lonoGuard[™] technology mitigates ionospheric GNSS signal disruptions.
- Data logging internally and to external drive. USB-C PD charging. Convenient 4-line front panel display and configuration.

Connected

- Multiple real-time corrections options: Trimble CenterPoint® RTX, Fugro Marinestar, Trimble VRS Now™, Internet Base Station Service (IBSS) or MSK Beacon GNSS correction services.
- Wi-Fi®, Bluetooth®, MSK Beacon and 4G LTE communications
- Integrated worldwide 4G LTE modem.
- Ethernet, serial and USB support.
- Trimble CenterPoint RTX correction service delivers global RTK-level precision without a base station or real-time network.
- Trimble xFill® correction outage technology.
- Stream RTK corrections over the internet with the Trimble Internet Base Station Service (IBSS).

Flexible

- All-in-one unit saving space and power requirements.
- Weatherproof, high-impact resistant marine alloy housing for protection from extreme conditions.
- Precise GNSS heading with optional INS.
- Modular form factor for flexible use on machines, vessels or vehicles.



Trimble MPS566 Model 2

Modular GNSS heading receiver

Configuration option			
MODULAR			
Base and rover interchangeability	Yes	Rover operation within a VRS network	Yes
Rover position update rate	1 Hz, 2 Hz, 5 Hz, 10 Hz, 20Hz, 50Hz	Heading and Moving Base operation	Yes
Rover maximum range from base	Unrestricted	Internal Memory	9.25 GB logging

General					
KEYBOARD AND DISPLAY					
	OLED Display (256 x 64), 32 characters by 4 rows				
	On/Off key for one-button startup				
	Escape and Enter keys for menu navigation				
	4 arrow keys (up, down, left, right) for option scrolls and data entry				
Dimensions (L × W × D)	269 mm (10.6 in) L x 141 mm (5.5 in) W x 61 mm (2.4 in) H				
Weight	1.85 kg (4.08 lb)				
GNSS ANTENNA (RECOMMENDED					
Zephyr [™] 3 or Zephyr Model 2 series [Base, Rover, Rugged, Geodetic]	Triple-frequency GNSS (GPS, GLONASS, Galileo, BeiDou, QZSS, NavIC) MSS, SBAS				
GA830	Triple-frequency GNSS (GLONASS, Galileo, BeiDou, QZSS), MSS, SBAS, MSK Beacon				
LNA Filters	Japanese LTE filtering below 1510 MHz allows useage >100m from LTE cell tower Iridium filtering above 1616 MHz allows usage >20m from Iridium transmitter				
TEMPERATURE					
Operating ¹	-40 °C to +65 °C (-40 °F to +149 °F)				
Storage	-40 °C to +80 °C (-40 °F to +176 °F)				
Humidity	93% humidity at 40 °C for a duration of 3 hours (IEC-60945 Method 8.3)				
Water Ingress Protection	IP67 for submersion to depth of 1 m (3.3 ft), dustproof				
SHOCK AND VIBRATION					
Pole Drop	Designed to survive a 1.1 m (3.6 ft) pole drop onto a hard surface				
Shock - Non-operating	To 75 g, 6 ms				
Shock - Operating	To 40 g, 10 ms, saw-tooth				
Vibration	IEC 60945 Method 8.7, Random 6.2 g RMS operating, 9.8g RMS 24-2000 Hz for 1 hrs each axis survival				

GNSS technology

Advanced Trimble Maxwell 7 Custom GNSS Chip

High-precision multiple correlator for GNSS pseudorange measurements

 $Unfiltered, unsmoothed \ pseudo-range \ measurements \ data \ for \ low \ noise, low \ multipath \ error, \ low-time \ domain \ correlation, \ and \ high-dynamic \ response$

Trimble EVEREST multipath signal rejection

Trimble IonoGuard technology for mitigation of ionospheric GNSS signal disruptions

Spectrum Analyser to troubleshoot GNSS jamming

Anti-spoofing capabilities

Japanese LTE filtering below 1510 MHz allows useage >100m from LTE cell tower

Iridium filtering above 1616 MHz allows usage >20m from Iridium transmitter

Trimble xFill technology for short gaps in correction messages

Advanced Trimble dual Maxwell 7 GNSS chipset provide 672 channels for simultaneous satellite tracking and anti-spoofing capabilities

GPS: L1 C/A, L1C, L2C, L5, L2E (Trimble method for tracking unencrypted L2P)

GLONASS: L1-C/A, L2-C/A, L1P, L2P, L3 Full Cycle Carrier

NavIC (IRNSS): L5-C/A

Galileo: E1, E5-A, E5-B, E5-AltBOC, E6

BeiDou: B1, B2, B3, B1C. B2A, B2B [Tracks 3rd generation BeiDou signals]

4-channel SBAS L1 C/A, L5 (WAAS/EGNOS/MSAS/GAGAN)

QZSS: L1 C/A, L1C, L1 SAIF, L2C, L5, L6

Dual MSS Band: Trimble CenterPoint RTX, OmniSTAR® and Fugro Marinestar correction services by subscription

Dual Channel MSK

Positioning				
REGIONAL SBAS POSITIONING ²	WAAS, MSAS, EGNOS, QZSS, GAGAN, SDCM, SouthPAN			
Accuracy	Horizontal \pm 0.50m (1.6 ft), Vertical \pm 0.85m (2.8 ft)			
PRECISE POINT POSITIONING (PPP) - UPGRADE REQUIRED				
Galileo HAS, SL1 [global]	Galileo HAS, SL1 [global] Horizontal ± 0.20m (0.7 ft), Vertical ± 0.40m (1.3 ft), Convergnce 300s			
QZSS CLAS [Japan only]	Horizontal 0.07m (0.2 ft) RMS, Vertical ± 0.12m (0.4ft) RMS			



Horizontal accuracy	OSITIONING ³					
accaracy	±(0.25m + 1 ppm) RMS :	±(0.8 ft + 1 ppm), :	±(250+1xDx10 ⁻⁶) mr	n [D = distance from base in Km]		
Vertical accuracy	±(0.50m + 1 ppm) RMS :	$\pm (0.50m + 1 \text{ ppm}) \text{ RMS } \pm (1.6 \text{ ft} + 1 \text{ ppm}),$ $\pm (500+1xDx10^6) \text{ mm } \text{ [D = distance from based]}$				
OMNISTAR/MARINESTAR PO	OSITIONING					
VBS service accuracy	Horizontal <1 m (3.3 ft)	HP service accur	racy	Horizontal 0.1 m (0.33 ft), Vertical 0.15 m (0.5 ft)		
XP service accuracy	Horizontal 0.2 m (0.66 f Vertical 0.3 m (1.0 ft)	t), Marinestar G2+	service accuracy	Horizontal 0.02 m (0.06 ft), Vertical 0.06 m (0.20 ft), 95%		
CENTERPOINT RTX POSITIO	NING ⁴					
Convergence time for specified precisions		<1 min [RTX Fast regions], <3 min [Worldwide]				
CenterPoint RTX accuracy (with valid subscription)		Horizontal 0.02m	Horizontal 0.02m (0.06 ft) RMS, Vertical 0.03m (0.1 ft) RMS			
xFill mode (limited to 5 minutes)		RTK Horizontal + 10 mm(0.03 ft)/min RMS. RTK Vertical + 20 mm(0.06 ft)/min RMS				
xFill-RTX mode (with valid	CenterPoint RTX subscription)	Horizontal 0.03m	ı (0.01 ft) RMS, Verti	ical 0.07m (0.2 ft) RMS		
REAL-TIME KINEMATIC POSI	TIONING ³ PRECISE ROVER					
Horizontal accuracy	8 mm + 1 ppm RMS (0.0)26 ft + 1 ppm RMS),	±(8+1xDx10 ⁻⁶) m	nm [D = distance from base in Km]		
Vertical accuracy	15 mm + 1 ppm RMS (0.	.05 ft +1 ppm RMS),	±(15+1xDx10 ⁻⁶)	mm [D = distance from base in Km]		
NETWORKED RTK ⁵ PRECISE F	ROVER					
Horizontal accuracy	8 mm + 0.5 ppm RMS,	±(8+0.5xDx10-6) m	m [D = distance fro	m base in Km]		
Vertical accuracy	15 mm + 0.5 ppm RMS,	±(15+0.5xDx10-6) r	mm [D = distance fr	om base in Km]		
FAST STATIC PRECISE ROVER	}					
Horizontal accuracy	3 mm + 0.5 ppm RMS,	±(3+0.5xDx10 ⁻⁶) m	m [D = distance fro	m base in Km]		
Vertical accuracy	5 mm + 0.5 ppm RMS,	±(5+0.5xDx10 ⁻⁶) m	m [D = distance fro	m base in Km]		
HIGH PRECISION STATIC PRE		,		<u>-</u>		
Horizontal accuracy	3 mm + 0.1 ppm RMS (0	0.01 ft +0.1 ppm).	±(3+0.1xDx10-6)	mm [D = distance from base in Km]		
Vertical accuracy	3.5 mm + 0.4 ppm RMS	• • • • • • • • • • • • • • • • • • • •		6) mm [D = distance from base in Km		
	AL OR WITH INCOMING MOVING BA		· ·	, [2 2.22		
Heading precision, 2m base				O OE° DMS (INC particul		
Heading precision, 10m bas		Pitch / Roll precis	sion (INS enabled)	0.05° RMS (INS option) or 1° RMS (Attitude option)		
VELOCITY	5.05 NVIS					
Doppler	H 0.008 m/s RMS, V 0.02	25 m/s RMS				
	11 0.000 111/5 KIVI3, V 0.02	CININ S IIII S				
INITIALIZATION TIME		Initialization		2-8 seconds		
Regular RTK operation with base station	Single/Multi-base	Initialization rel	iability ⁶	>99.9%		
Power						
POWER						
External	Power input on 7-pin 0-shell Lemo Maximum 28 VDC	o connector is optimize	ed for lead acid bat	teries with a cut-off threshold of 11.5		
	Dower input on the 20 pin D sub a	Power input on the 26-pin D-sub connector is optimized for Trimble lithium-ion battery input with a cut-off hreshold of 10.5 V				
	threshold of 10.5 V					
		ernal) is hot-swap cap	able in the event of	<u> </u>		
	threshold of 10.5 V	, , ,	able in the event of	<u> </u>		
	threshold of 10.5 V Power source supply (Internal/Ext	e of 15 V @ 2 A	able in the event of	<u> </u>		
	threshold of 10.5 V Power source supply (Internal/Ext USB-PD input from device capable	e of 15 V @ 2 A		<u> </u>		
Power consumption	threshold of 10.5 V Power source supply (Internal/Ext USB-PD input from device capable DC external power input with over	e of 15 V @ 2 A r-voltage protection when connected to exte		<u> </u>		
Power consumption	threshold of 10.5 V Power source supply (Internal/Ext USB-PD input from device capable DC external power input with over Receiver automatically turns on w 7.7 W in rover mode, dual GNSS and	e of 15 V @ 2 A r-voltage protection rhen connected to extend	ernal power	<u> </u>		
	threshold of 10.5 V Power source supply (Internal/Ext USB-PD input from device capable DC external power input with over Receiver automatically turns on w 7.7 W in rover mode, dual GNSS a 8.0 W in rover mode with internal	e of 15 V @ 2 A r-voltage protection rhen connected to extend	ernal power			
Communications REGULATORY APPROVALS	threshold of 10.5 V Power source supply (Internal/Ext USB-PD input from device capable DC external power input with over Receiver automatically turns on w 7.7 W in rover mode, dual GNSS and	e of 15 V @ 2 A r-voltage protection rhen connected to extend	ernal power			
Power consumption Communications REGULATORY APPROVALS COMMUNICATIONS Serial 1 (COM1)	threshold of 10.5 V Power source supply (Internal/Ext USB-PD input from device capable DC external power input with over Receiver automatically turns on w 7.7 W in rover mode, dual GNSS a 8.0 W in rover mode with internal	e of 15 V @ 2 A r-voltage protection then connected to extended receive radio, dual GN	ernal power	power source removal or cut off 26-pin D-sub, Serial 2,		
Communications REGULATORY APPROVALS COMMUNICATIONS	threshold of 10.5 V Power source supply (Internal/Ext USB-PD input from device capable DC external power input with over Receiver automatically turns on w 7.7 W in rover mode, dual GNSS at 8.0 W in rover mode with internal	e of 15 V @ 2 A re-voltage protection when connected to extend to	ernal power ISS active rial 2 (COM2)	power source removal or cut off		

Communications (c	continued)		
USB	USB v2 (Supports USB-PD)	Ethernet	Through a multi-port adaptor (PN 57168)
Wi-Fi	Fully-integrated, fully-sealed 2.4 GHz Wi-Fi module Simultaneous Access Point (AP) and Client modes	Bluetooth wireless technology	Fully-integrated, fully-sealed 2.4 GH Bluetooth module ⁷
Internal LTE Modem	Fully-integrated, fully-sealed LTE compliant module, Nano-SIN FDD-LTE: bands 1, 2, 3, 4, 5, 7, 8, 12, 13, 18, 19, 20, 26, 28, 66 TD-LTE: b		vi card pands 38, 40, 41 and GSM: 850, 900, 1800, 1900 MHz
NETWORK PROTOCOLS			
HTTP (web browser GUI)	HTTP, HTTPS	mDNS/uPnP Service discovery	Yes
NTP Server	Yes	Dynamic DNS	Yes
TCP/IP or UDP	Yes	Email alerts	Supports SSL/TLS
NTRIP	NTRIP v1 and v2, Client, Server and Caster modes	Eman alerts	secure email servers
INTEGRATED UHF RADIO			
	Fully-integrated internal 403-473 MHz or dual band	403-473 MHz / 902-928	MHz; Rx/Tx
450 MHz	12.5 kHz or 25 kHz spacing available		
Sensitivity	-114 dBm (12 dB SINAD)	900 MHz	Fully-integrated, internal 900 MHz; Tx/Rx [1.0 W]
Transmit power (450 MHz)	0.5 W, 1.0 W [Configured by Trimble Dealer]		1.710x [1.0 W]
Frequency approvals (403-473 MHz)	Worldwide and depending on the local required licensing	Frequency approvals (902-928 MHz)	USA/Canada/Australia
INTERNAL MSS DEMODULATO	OR (L-BAND)		
Channels	2	Correction Services	Trimble CenterPoint RTX, OmniSTAF
Frequency range	1525-1559 MHz	Correction Services	and Fugro Marinestar
INTERNAL MSK BEACON RECI	EIVER		
Channels	2	MSK bit rate	50, 100, and 200 bps
Frequency range	283.5-325.0 kHz	Demodulation	Minimum shift key (MSK)
Channel spacing	500 Hz	Antenna	Trimble GA830
CELLULAR SUPPORT			
Internet-based correction streams: (IBSS, VRS, NTRIP)	Internal LTE modem Connected smartphone Connected Trimble Controller [Trimble SiteWorks, 7	「rimble Access™]	
Remote Access	Using DynDNS and appropriate service		
INPUT/OUTPUT			
Correction inputs	CMR, CMR+™, CMRx, RTCM 2.x, RTCM 3, RTCM 3.3(MSM); MSS [Marinestar, Trimble CenterPoint RTX]	Data outputs	NMEA 0183, NMEA 2000, GSOF, 1PPS Time Tags, RT17, RT27
Maximum data rate	100Hz (depending on data type)	Data inputs	Event
FEATURES AND UPGRADES			
Standard features	RTX Rover, GPS, GLN, BDS, GAL, QZSS, SBAS, 3F, xFill, Wi-Fi (AP, Client), LTE, Logging	Signal / Constellation upgrades	All constellations and signals are included as standard
Raw data logging (*.T02, *.T04)	9.25 GB internal, expandable using USB-C flash drive (e.g. 32 GB)	-	Inertial (INS) heading, pitch and roll Attitude, 1° pitch and roll Programmatic interface Binary ouputs
Precision upgrades	Precise Heading Rover with Base as backup 10/02 Heading Rover 10/10 Heading Rover	Feature upgrades	

- 1. Operating up to +65 °C ambient when the device is powered by external DC supply Operating up to +48 °C ambient when the device is powered by a USB-PD battery or charger.
- 2. Depends on SBAS system performance.
- 3. Accuracy and reliability may be subject to anomalies such as multipath, obstructions, satellite geometry, interference and atmospheric conditions. Always follow recommended survey practices.
- 4. Receiver accuracy and convergence time varies based on GNSS constellation health, level of multipath, and proximity to obstructions such as large trees and buildings.
- 5. Networked RTK PPM values are referenced to the closest physical base station.
- 6. May be affected by atmospheric conditions, signal multipath, and satellite geometry. Initialization reliability is continuously monitored to ensure highest quality.
- 7. Bluetooth type approvals are country specific. For more information, contact your local Trimble office or representative.



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